

PHONONS → DIAGNOLIZATION ①

I) QUANT. MECH. & OF COUPLED SYSTEM  
 STAT. MECH. COUPLON HAMILTONIAN  
 N-PARTICLE SYSTEMS

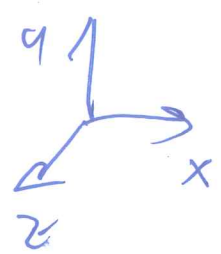
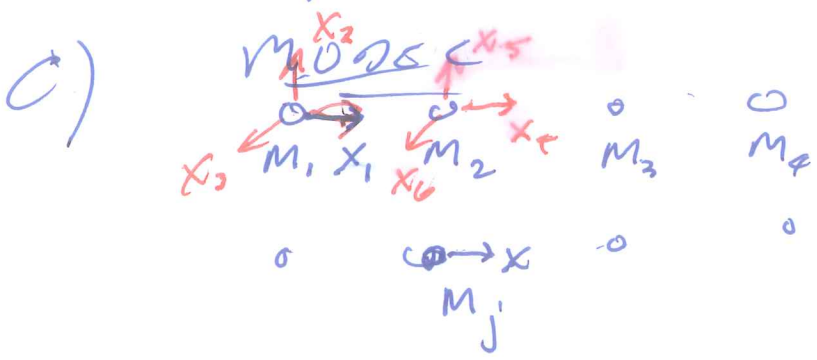
A) Refs. Reif : ch. 10 \*  
 Hill : ch. 5 Einstein

WILSON & BARROTT  
 ADV. ENGINEERING MATH  
 pg. 734

model  
 ↓  
 HIGH FREQ  
 LIQUIDS

B) PHONONS  
 - PHYSICS  
 - MATH  
 - REVIEW

$T < 10^{-14} s$



array atoms  
 cubic lattice in solid

D) Focus on how to carry 2

CONSERVATIVE DYNAMICS:

~~2x~~

2x

$$H_{\text{sys}} = \frac{1}{2} \sum m_i \dot{x}_i^2 + V(x_1, x_2, x_3, \dots, x_{3N-2}, x_{3N-1}, x_{3N})$$

5) Ref: Assume small oscillations

a)  $V(x_1, \dots, x_{3N}) = V(x_{10}, x_{20}, x_{30}, \dots, x_{3N0})$

$x_{j0} = \text{equil mag of } x_j$

$\frac{\partial V}{\partial x_j} = \text{Force in } x_j$   
on ~~what~~ ~~pt~~ ~~of~~ ~~mass~~ ~~at~~ ~~all~~ ~~pts~~

$+ \sum_{j=1}^{3N} \frac{\partial V}{\partial x_j} \Big|_{x_{j0}} = 0$

$+ \frac{1}{2} \sum_{i,j=1}^{3N} \left( \frac{\partial^2 V}{\partial x_i \partial x_j} \Big|_{x_{i0}, x_{j0}} \right) x_{i0} x_{j0} + O(x_i^3)$

rel error  $O\left(\frac{x_i^3}{x_j^2}\right)$   
 $\sim O(x_i^3 x_j^{-2})$

$$b) \therefore \left( V(\dots) = V_0 + \frac{1}{2} \sum_{i,j} V_{ij} x_i x_j \right) \quad (3)$$

$$V_{ij} \equiv \frac{\partial^2 V}{\partial x_i \partial x_j} \Big|_{\text{equil}}$$

c) b) in matrix form:

$$(3.1) \left( V(\dots) = V_0 + \frac{1}{2} \underline{x}^T \underline{V} \underline{x} \right) \quad \begin{matrix} * \\ * \end{matrix}$$

$$d) \therefore \underline{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{3N} \end{bmatrix} \quad \underline{x}^T = [x_1 \ x_2 \ \dots \ x_{3N}]$$

NOTE: V is symmetric  
 why? is  $V_{ij} = V_{ji}$ ? check

e)  $KE_{sys} = \frac{1}{2} \sum_i m_i \dot{x}_i^2$

f)  $KE_{sys} = \underbrace{\begin{bmatrix} \dot{x}_1 & \dot{x}_2 & \dot{x}_3 & \dots & \dot{x}_{3N} \end{bmatrix}}_{\dot{\underline{x}}^T} \begin{bmatrix} m_1 & 0 & 0 & 0 & 0 & 0 \\ 0 & m_2 & 0 & 0 & \dots & 0 \\ 0 & 0 & m_3 & 0 & \dots & 0 \\ \vdots & & & \ddots & & \vdots \\ \dots & & & & m_N & \dots \end{bmatrix} \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \\ \vdots \\ \dot{x}_{3N} \end{bmatrix}$

3N ↓  $\dot{\underline{x}}$

3N →

$\frac{1}{2} \dot{\underline{x}}^T$

g)  $KE_{sys} = \frac{1}{2} \dot{\underline{x}}^T \underline{M} \dot{\underline{x}}$  (9.1)

⊕ M IS ALSO SYMMETRIC

$\begin{bmatrix} m_1 \dot{x}_1 \\ m_1 \dot{x}_2 \\ m_1 \dot{x}_3 \\ m_2 \dot{x}_4 \\ \vdots \\ m_N \dot{x}_{3N} \end{bmatrix}$

$\frac{1}{2} [m_1 \dot{x}_1^2 + m_2 \dot{x}_2^2 + m_1 \dot{x}_3^2 + \dots + m_N \dot{x}_{3N}^2]$

∴ II)

$$M_{sys} = \frac{1}{2} \dot{x}^T \underline{M} \dot{x} + V_0 + \frac{1}{2} x^T \underline{V} x \quad (5.1)$$

B) FROM MINIMUM PRINCIPLE:

JMM

a) Let  $\underline{M}$  and  $\underline{V}$  BE

$3 \times 3$  - SYMM. MATRICES

b)  $\underline{V}$  POSITIVE DEF

c) THEN FOR FOLLOWING  
EQUATION

~~Equation~~  $\downarrow$  <sup>positional</sup>  $\downarrow$  <sup>eigenvector</sup>

$$(5.1) \left[ \underline{V} - n \underline{M} \right] \underline{a} = \underline{0}$$

~~Let~~  $\underline{a} = \underline{E} \underline{d}$

Answer

(6)

d) (5.1)  $\Rightarrow$  characteristic  
eqn in  $\lambda$ :

$$\text{Det} \left[ \underline{V} - \lambda \underline{M} \right] = 0$$

$\Downarrow$

has  $3N$  real roots

$$\left[ \lambda_1, \lambda_2, \lambda_3, \dots, \lambda_{3N} \right]$$

e) to get the  $j^{\text{th}}$  eigenvector  
 $\underline{a}_j$  :

$$\left[ \underline{V} - \lambda_j \underline{M} \right] \underline{a}_j = \underline{0}$$

$$\boxed{\underline{a}_j} = \mathbb{R}^N \mathbb{Z}^N \times 1$$

---

Let  $\underline{A} = \left[ \underline{a}_1 \quad \underline{a}_2 \quad \underline{a}_3 \quad \dots \quad \underline{a}_{3N} \right]$   
 $(3N \times 3N)$

THM Result:

(7)

$$\underline{\underline{A}}^T \underline{\underline{V}} \underline{\underline{A}} = \underline{\underline{D}}$$

$$\underline{\underline{A}}^T \underline{\underline{M}} \underline{\underline{A}} = \underline{\underline{I}}$$

3x3  
↓

$$\underline{\underline{D}} = \begin{bmatrix} \lambda_1 & 0 & & & \\ 0 & \lambda_2 & & & \\ 0 & 0 & \lambda_3 & 0 & 0 \\ & & & \ddots & \\ 0 & & & & \ddots \end{bmatrix}$$

3x3 →

$$\begin{bmatrix} 0 \\ \vdots \\ \lambda_{3 \times 3} \end{bmatrix}$$

$$\underline{\underline{I}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ & & & \ddots & \\ & & & & \ddots \end{bmatrix}$$

$$\begin{bmatrix} \\ \\ \\ \ddots \\ \end{bmatrix}$$

III) now,  
 A) let

$$\underline{x} = \underline{A} \underline{x}' \quad \text{uncoupled coord.} \quad (8.1)$$

$$\Rightarrow \underline{\dot{x}} = \underline{A} \underline{\dot{x}'} \quad (8.2)$$

$$\Rightarrow \begin{aligned} \underline{x}^T &= (\underline{A} \underline{x}')^T \\ &= (\underline{x}')^T \underline{A}^T \\ \underline{\dot{x}}^T &= (\underline{A} \underline{\dot{x}'})^T \\ &= \underline{\dot{x}'}^T \underline{A}^T \end{aligned} \quad (8.3)$$

$$B) H_{\text{orig}} = \frac{1}{2} \underline{\dot{x}}^T \underline{M} \underline{\dot{x}} + \frac{1}{2} \underline{x}^T \underline{V} \underline{x}$$

$$\begin{aligned} H_{\text{sub}} &= \frac{1}{2} \underline{\dot{x}'}^T \underline{A}^T \underline{M} \underline{A} \underline{\dot{x}'} + U_0 \\ &+ \frac{1}{2} \underline{x}'^T \underline{A}^T \underline{V} \underline{A} \underline{x}' + V_0 \end{aligned}$$





9 . . . .

physics  
solid state physics  
Great illustration of  
physics

previd  
with 555  
took 4/10/23

1)  $V_{sys} = V(x_1, x_2, x_3, \dots, x_{3N-2}, x_{3N-1}, x_{3N})$

3 - num coord

1) Figure out  $H_{sys} \rightarrow$  place in eigen

2) use  $1/m \rightarrow H_{sys}$  in decoupling form  $\Rightarrow$  [5N harmonic oscillators]

3) Diagnose :  $\frac{L_{total}}{h\nu}$

4) write down S.O. for single

oscillator  $\frac{p^2}{2m} + K\tilde{x}$

$$\left[ \frac{p^2}{2m_i} \nabla^2 \psi_i - \omega^2 m \tilde{x}^2 \psi = E \psi \right]$$



$$\left[ E_{\alpha}^{(n)} = \left( n + \frac{1}{2} \right) h \omega \right]$$

$$1) H = V(\underline{x}) + \frac{1}{2} \sum m_s \dot{x}_s^2$$

Ⓟ

$$2) V(\underline{x}) = V_0 + \frac{1}{2} \sum_{i,j} V_{ij} x_i x_j$$

$$V_{ij} = V_{ji}$$

3) ~~$$K = \frac{1}{2} \begin{bmatrix} \dot{x}_1 & \dot{x}_2 & \dot{x}_3 & \dots \end{bmatrix} \begin{bmatrix} m_1 & & & \\ & m_2 & & \\ & & m_3 & \\ & & & \ddots \end{bmatrix}$$~~

~~$$\dot{x}_j = \sqrt{m_j} \dot{X}_j$$~~

~~$$X_j = \frac{1}{\sqrt{m_j}} \dot{x}_j$$~~

~~or~~

4) 
$$H = \underline{\dot{x}}^T \underline{K} \underline{\dot{x}} + \frac{1}{2} \underline{x}^T \underline{V} \underline{x} + V_0$$

$$= \frac{1}{2} \underline{\dot{x}}^T \underline{M} \underline{\dot{x}} + \frac{1}{2} \underline{x}^T \underline{V} \underline{x} + V_0$$

5) Thom: 
$$\underline{[M - \lambda V]} = \underline{0}$$
  $\underline{M}, \underline{V}$   
symmetric  
and  $\underline{V}$   
pos. def.

a)  $\det \underline{[M - \lambda V]} = 0 \Rightarrow \lambda_1, \lambda_2, \lambda_3, \dots$

c) solve  $\underline{[M - \lambda_i V]} \underline{a} = \underline{0} \Rightarrow \underline{a}_1, \underline{a}_2, \underline{a}_3, \dots$

$$d) \underline{A} = [\underline{a}_1 \quad \underline{a}_2 \quad \underline{a}_3 \quad \dots \quad \underline{a}_{3n}]$$

③

e) From

$$\left[ \begin{array}{l} \underline{A}^T \underline{M} \underline{A} = \underline{D} \\ \underline{A}^T \underline{A} = \underline{I} \end{array} \right]$$

$$\underline{D} = \begin{bmatrix} d_1 & & & \\ & d_2 & & \\ & & \ddots & \\ & & & d_{3n} \end{bmatrix}$$

←

6) Let

$$\underline{x}' = \underline{A} \underline{x}$$

⇒

$$\underline{x} = \underline{A} \underline{x}'$$

$$\left[ \begin{array}{l} \underline{x} = \underline{A} \underline{x}' \\ \dot{\underline{x}} = \underline{A} \dot{\underline{x}}' \end{array} \right]$$

$$7) \therefore 4) \Rightarrow \frac{1}{2} \dot{\underline{x}}^T \underline{M} \dot{\underline{x}} + V_0 + \frac{1}{2} \underline{x}^T \underline{V} \underline{x} = H_{\text{mech}}$$

$$\Rightarrow \frac{1}{2} (\underline{A} \dot{\underline{x}}')^T \underline{M} \underline{A} \dot{\underline{x}}' + V_0 + \frac{1}{2} (\underline{A} \underline{x}')^T \underline{V} \underline{A} \underline{x}' = H_{\text{mech}}$$

$$\Rightarrow \frac{1}{2} (\dot{\underline{x}}')^T \underline{A}^T \underline{M} \underline{A} \dot{\underline{x}}' + V_0 + \frac{1}{2} (\underline{x}')^T \underline{A}^T \underline{V} \underline{A} \underline{x}' = H_{\text{mech}}$$

Ⓞ

$$\& \therefore H_{sys} = \frac{1}{2} (\dot{x}')^T \underline{M} \dot{x}' + \frac{1}{2} \underline{x}'^T \underline{K} \underline{x}' + U_0$$

9) GO BACK LAB AND

SOLVE

$$\underline{[V - MM]} \underline{q} = \underline{0}$$

$$\Rightarrow H_{sys} = \frac{1}{2} \underline{x}'^T \cdot \underline{x}' +$$

$$\Rightarrow \begin{bmatrix} x'_1 & x'_2 & \dots \end{bmatrix} \begin{bmatrix} d_1 x'_1 \\ d_2 x'_2 \end{bmatrix} \quad \frac{1}{2} (\underline{x}'^T) \left[ \begin{array}{c} d_1 x'_1 \\ d_2 x'_2 \end{array} \right] + U_0$$

$$H_{sys} = \frac{1}{2} \sum_{j=1}^n \dot{x}'_j \dot{x}'_j + \left[ \frac{1}{2} \sum_{j=1}^n d_j x'^2_j + U_0 \right]$$

$$H_{sys} = H_{p1} + H_{p2} + H_{p3} + \dots + H_{pn}$$

$$\text{Ⓞ} \quad H_{pk} = \frac{1}{2} \dot{x}'_k{}^2 + \frac{d_k}{2} x'^2_k + U'_0$$

to get ~~it~~ into S-form and  
 form

(4a)

go back and

define  $\tilde{x}_j = \sqrt{m} x_j \Rightarrow x_j = \frac{1}{\sqrt{m}} \tilde{x}_j$

$\Rightarrow X = \frac{1}{\sqrt{m}} \tilde{X}$        $X = A X'$

$\therefore \tilde{x}_k' \tilde{x}_k = m$

$\Rightarrow \tilde{X} = \sqrt{m} X = \sqrt{m} A X'$

$\tilde{X}' = \sqrt{m} A' X'$

$\underline{\underline{M}}$

d. course

(5)

$$l_{\text{th}} \sim 5 \text{ \AA}$$

2 calc  
S.T

1)  $k_B \sim V \sim \frac{E}{k_B T}$

2)  $\frac{\hbar^2 \psi^2}{2m_k} + V_k \psi = E_k \psi$

$$\rightarrow \frac{\hbar^2 \psi^2}{2m_k} \sim k_B T$$

$$\rightarrow \lambda_{\text{th}} \sim \frac{\hbar}{\sqrt{2m_k k_B T}}$$

$$\lambda_{\text{th}} \sim 10^{-34} \text{ s}$$

$$m_k = \frac{63 \text{ kg}}{10^{26} \text{ kg mol}} = 6(10^{-25}) \text{ kg}$$

$$\lambda_{\text{th}} \sim 10^{-34} \text{ s}$$

$$\sqrt{(12)(10^{-25}) \text{ kg} (1.34) \frac{\text{kg m}^2/\text{s}^2}{\text{kg}} \cdot 300 \cdot 10^{23}}$$

$$(3)(50) 10^{-46}$$

$$\sim \frac{10^{-34}}{(7) 10^{-23}} \sim 1.4(10^{-11}) \text{ m} \sim 0.15 \text{ \AA}$$